ACAMS - INTEGRATED SOFTWARE FOR ACCELERATOR ALIGNMENT AND MEASUREMENT

K. Tremblay, K. S. Baggett and C. J. Curtis

Thomas Jefferson National Accelerator Facility, 12000 Jefferson Avenue, Newport News, Virginia 23606, USA

Abstract

ACAMS (Accelerator Combined Alignment and Measurement System) is a software package that has been developed at Thomas Jefferson National Accelerator Facility (Jefferson Lab). ACAMS was developed to replace four dos based software programs. These programs operated independently and all used theodolite observations as the common basis for data collection. The methodology used to collect the data was similar, but there were

ACAMS now integrates all the reductions, adjustment and reporting into one package. Jefferson Lab Alignment group now relies on ACAMS for most of the field surveys undertaken. Many new features that were lacking in the older packages have been included in the development of ACAMS. This aper will discuss the reasoning behind the development, current available features, and the future direction that the software will take.

Project Type Options



Figure 1 – Project Type Selection Menu

Operators must choose from the list of options as shown in figure 1. There are 4 main options which start new survey projects. They are, New Fiducial File, Step 2 (magnet alignment), Step 1 (stand alignment) or Spectrometer surveys. Additional options are for appending or resuming a project, using an existing control file to start a new project, choosing to open a project which wasn't the last, or importing project control and target information.

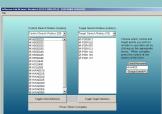


Figure 3 – Stand Alignment (step 1) Option

Figure 3 – saint originities, (step 1) Option For step 1 projects, the user can simply enter a centrally located stand, or control monument, and the program will check through a database of stand or pedestal coordinate data. All the relevant components are then displayed in the right hand list box, and available monuments in the localized area are displayed in the left box. The user can then pick and choose which information to include in the project.

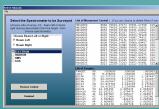




Figure 2 — Fiducialization Option
This option illustrates the menu available when fiducializing objects. Users can generate a group of points and Theodolite ID tags (numeric) at this point. Groups of points can automatically be generated. Scale bars are also numerated at this point.



Figure 4 - Magnet Alignment (step 2) Option

Figure 4 displays 2 screens that users navigate through when conducting Step 2 style surveys. The top illustration shows how the Lab's accelerators are sectionalized into areas, which are again broken into sectors within each area. Individual component information is then available to the users to select from each sector. Finally, individual targets on the components can be selected. The second portion of the illustration, shows the autonumbering and editing facility available to the users.



Project information is added to the job files with this screen. Every style of project uses this common menu.

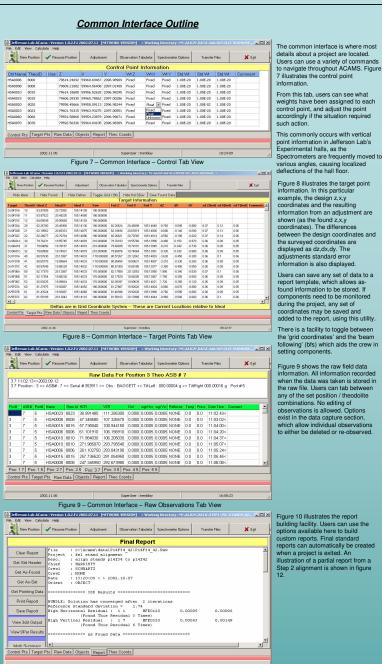
CONCLUSIONS

With approximately a half man-years of coding investment, ACAMS has combined several disjointed field operations and procedures into a tightly integrated operation. Additions have been made to the software, which have provided several new and valuable tools to the users. The crews have commented on the software's ease of use, the ability to rapidly align components, and conduct other essential alignment tasks.

ACAMS was developed in order to integrate Jefferson Lab's existing theodolite based alignment software into one package. ACAMS is now the main tool used by the Alignment Group. The software has given Jefferson Lab a tool that fits it requirements, and traditional alignment operations while also allowing the group to have the flexibility and control over its development as circumstances dictate.

Future development that includes integration of updated and new equipment, and the ability to customization the software to specific tasks should nake ACAMS a tool that will be used at the lab for many years.

I would like to thank and recognize the alignment group at the Stanford Linear Accelerator for supplying the original code for the bundling program 3DCD, and a particular thanks to Catherine Le Cocq for the use of the WINFIT program. A special thanks also goes out to all the field staff at the lab for their patience, suggestions and verification of all the processes developed for ACams.



ontrol Pts Target Pts Raw Data Objects Report Theo Coords

Theodolite data collection takes place using the capture interface screens. Figure 14 shows the main data capture screen. Upon switching from the common interface via the resume or new position

commands, all available serial ports are automatically sensed to see what theodolites are attached and a display such as figure 14 comes up.

This commonly occurs with vertical point information in Jefferson Lab's Experimental halls, as the Spectrometers are frequently mo various angles, causing localized deflections of the hall floor.

Figure 8 illustrates the target point information. In this particular information. In this particula example, the design z,x,y coordinates and the resulting shown (as the found z,xy coordinates). The differences between the design coordinates and the surveyed coordinates are displayed as dz,dx,dy. The adjustments standard error information is also displayed.

Users can save any set of data to a report template, which allows as-found information to be stored. If components need to be monitored during the project, any set of coordinates may be saved and added to the report, using this utility.

There is a facility to toggle between the 'grid coordinates' and the 'beam following' (bfs) which aids the crew is setting components.

One of the main features available in ACAMS is the Real Time Positioning (RTP) routine. This routine is used to position any object into its desired alignment. The procedure requires the crew to observe the control points, the components to be aligned, and obtain an adjustment from 3DCD. They can then use the 'RTP Toggle' option on the main data capture toolbar. This then takes the program to a new screen, figure 18, where the theodolites are polled at either set time intervals or the instrument operators take manual observations, to align a component to any given set of design coordinates.

As the instrument operators take observations, the coordinates are automatically updated, using a least squares solution. A value, based upon the original forward and reverse observations taken to the targets, is used to correct single face observations taken in RTP. The input file to 3DCD is updated with the corrected angles, and after the adjustment, the differences between design and the presently located target are calculated. The differences are then displayed as shown in figure 18, and the crew can make the necessary adjustments to the component, and iterate until the component is within an acceptable tolerance. After adjusting all the required elements by using the RTP routine, the crews will lock-down the elements and conduct a final survey using forward and reverse observations.

Capture Interface Outline

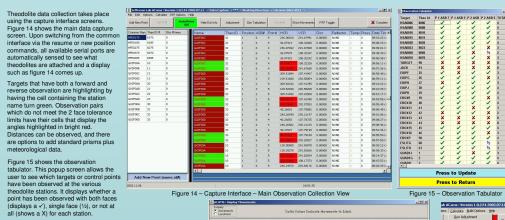


Figure 16 - Capture Interface - Movements Display View

Figure 16 illustrates the 'Display Movement' command view. Users can choose between displaying the difference between either 'movements' to set a particular component or the actual 'location' of the component. Information showing the standard errors of the target point is also

A additional feature currently being developed, is to tie our fiducial database to the located components and then calculate the reverse least squares transformation to find the component center and rotation values. This information will be displayed in this screen.

Figure 17, shows the options available from one of the pull-down menus in the Capture Interface. From the 'Calculate' command, users can run a variety of fitting routines, distance calculations o

| Delicement & McConst Servicion 102/16 2000/1741 | Code1 Code2 2000/2741 | Code2 2000/274 RTP TARGET: GV2F0AA [using One Face method] dZ:-0.090 (mm) dX:-0.178 (mm)

dY:-0.550 (mm) Select Element Check Control Single Face On Target Recognition ON Calc Delta Diff

Figure 18 - Capture Interface - Real Time Positioning (RTP) View

Spectrometer Alignment Options

Jefferson Lab's Hall A contains two high resolution spectrometers and Hall C has a High Momentum (HMS) and a Short Orbit (SOS) spectrometer. All four spectrometers rotate about a central target. The alignment group is frequently called upon to determine the angle between the incoming beam and the centerline of the spectrometers. ACAMS is used to survey the spectrometer with respect to the local monuments. After a satisfactory adjustment with 3DCD, the results are processed using transformation software to determine the central axis of the spectrometers with respect to the beam. ACAMS automates this process resulting in smooth flow of information between processes.

Figure 19 shows the options that the crew steps through to calculate the desired spectrometer angle. Shown in figure 20 is the output from a Hall A Electron spectrometer survey. All the information required by the physici





Adjustment Details

Figure 22 illustrates the various views that can also be shown from this section of the program View options are capable of displaying the input file, adjusted

Figures 23 to 25 show the

